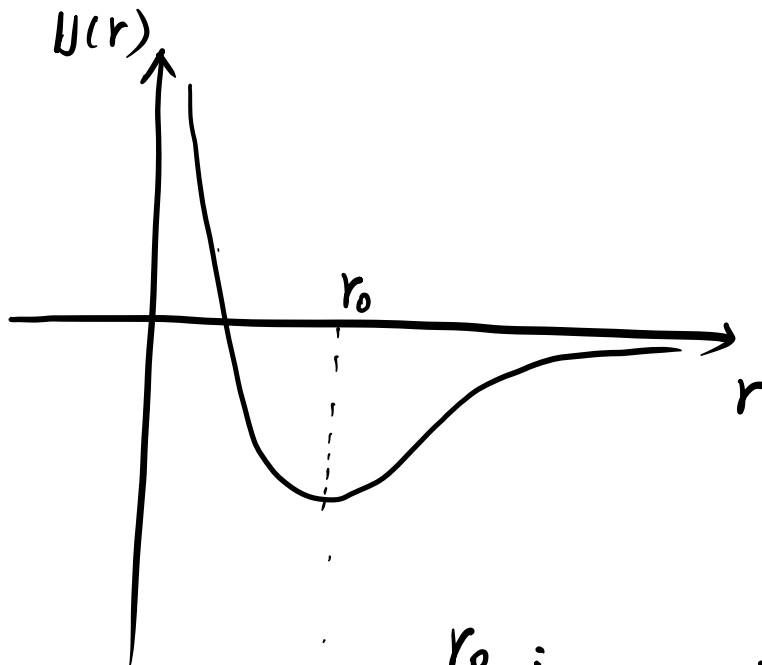
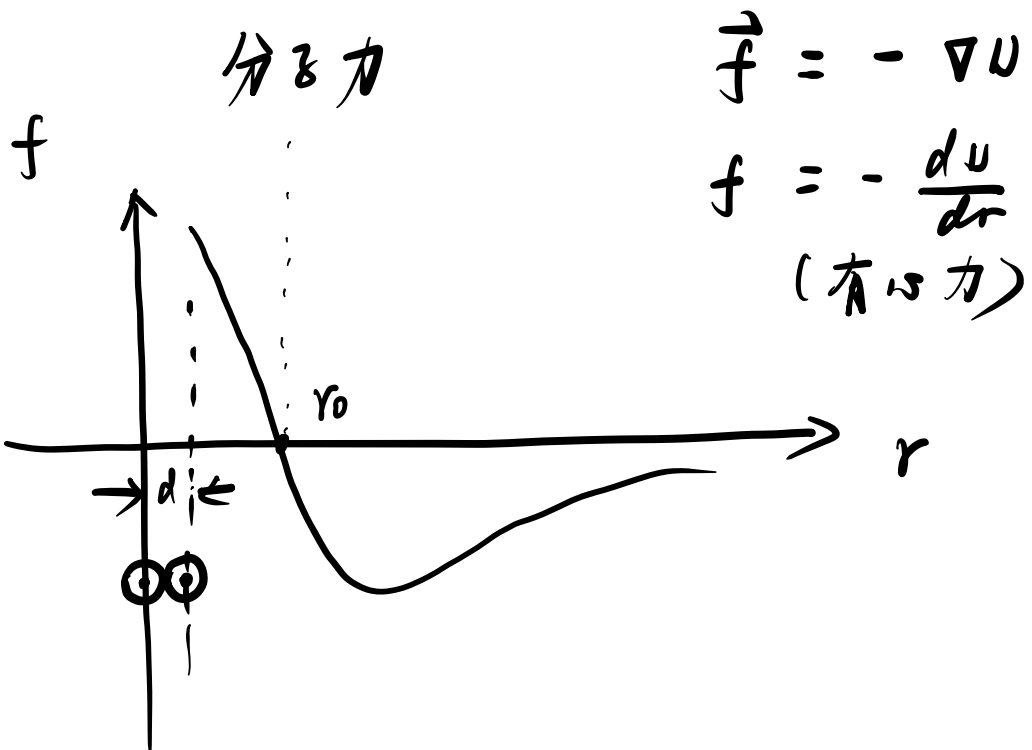


分子力势能曲线



$$r_0 : \quad \frac{dU(r)}{dr} = 0$$

平衡位置



$$\text{Q: } \vec{F} = \vec{i} x^2 y^3 + \vec{j} x y^2$$

是一个保守力吗？

if \vec{F} is a conservative force

$$F_x = - \frac{\partial U}{\partial x}, \quad F_y = - \frac{\partial U}{\partial y}$$

观察 \vec{i} 分量

$$U \sim x^3 y^3$$

观察 \vec{j} 分量

$$U \sim x y^3$$

no such U to satisfy the
two components

$$\frac{\partial U}{\partial y \partial x} = - \frac{\partial F_x}{\partial y}$$

||

$$\frac{\partial U}{\partial x \partial y} = - \frac{F_y}{\partial x} \Rightarrow$$

$$\frac{F_x}{\partial y} = \frac{F_y}{\partial x} \quad (\text{判据})$$

势能函数仅依赖于位置

dE_p : 在数学上意味着

一个全微分

这样的微分函数将与路径无关

积分结果仅与出发点, 目的地相关

讲过微分 again ^_^

Linear approximation

$$F(y) = F(y_0) + F'(y_0)(y - y_0)$$

Taylor expansion:

$$\begin{aligned} F(y) &= F(y_0) + F'(y_0)(y - y_0) + \frac{1}{2} F''(y_0)(y - y_0)^2 \\ &\quad + \dots + \frac{1}{n!} F^{(n)}(y_0)(y - y_0)^n + \dots \\ &= \sum_{n=0}^{\infty} \frac{1}{n!} F^{(n)}(y_0)(y - y_0)^n \end{aligned}$$

y 在 y_0 邻域, $\Delta y = y - y_0$ (smallness)

$(\Delta y)^n$: 高阶 (n) 小量

$$\nabla \equiv \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

$$\frac{\partial f(x, y, z)}{\partial x} = \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x, y, z) - f(x, y, z)}{\Delta x}$$

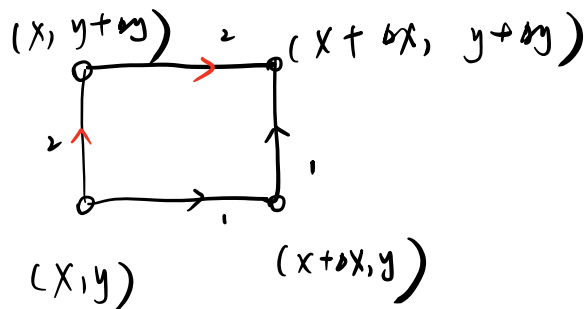
partial
derivative

(here, y, z keep invariant)

gradient (∇): 上升最快的方向 (势函数)

$$\vec{F} = -\nabla E_p$$

\vec{F} : 其方向是势能下降最快的方向



$$\text{路径 1: } f(x+dx, y+dy) - f(x, y)$$

$$= f(x+dx, y+dy) - f(x+dx, y)$$

$$+ f(x+dx, y) - f(x, y)$$

$$= \frac{\partial f}{\partial y} \bigg|_{x+dx, y} \Delta y + \frac{\partial f}{\partial x} \bigg|_{x, y} \Delta x$$

① ②

$$\text{路径 2: } f(x+dx, y+dy) - f(x, y)$$

$$= f(x+dx, y+dy) - f(x, y+dy)$$

$$+ f(x, y+\Delta y) - f(x, y)$$

$$= \frac{\partial f}{\partial x} \bigg|_{x, y+\Delta y} \Delta x + \frac{\partial f}{\partial y} \bigg|_{x, y} \Delta y$$

(3)(4)

$$\textcircled{1} + \textcircled{2} - \textcircled{3} - \textcircled{4} = 0$$

$$\textcircled{1} - \textcircled{4} = \frac{\partial}{\partial x} \frac{\partial f}{\partial y} \Delta x \Delta y$$

$$\textcircled{2} - \textcircled{3} = - \frac{\partial}{\partial y} \frac{\partial f}{\partial x} \Delta y \Delta x$$

↓↓

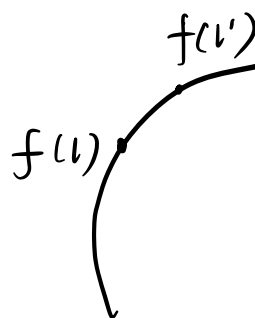
$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

$$\frac{\partial f}{\partial x} = -F_x, \quad \frac{\partial f}{\partial y} = -F_y$$

$$\frac{\partial F_x}{\partial y} = \frac{\partial F_y}{\partial x}$$

方向导数：

$$\frac{df}{d\vec{l}}$$



$$\textcircled{1} = \lim_{l \rightarrow l'} \frac{f(l') - f(l)}{\Delta l} \quad \uparrow$$

$$\textcircled{2} = (\nabla f \cdot \hat{l}) \hat{l}$$

E.g. $E_k = \frac{1}{2} m v^2 = \frac{1}{2} m \vec{v} \cdot \vec{v}$

计算 $\frac{\partial E_k}{\partial \vec{v}} = \frac{1}{2} m \left(\frac{\partial v^2}{\partial \vec{v}} \right)$

$$= \frac{1}{2} m (\nabla v^2 \cdot \hat{l}) \hat{l} \quad (\text{用等号 "=" } \textcircled{2})$$

$$= \frac{1}{2} m [(2v_x \hat{i} + 2v_y \hat{j} + 2v_z \hat{k}) \cdot \hat{l}] \hat{l}$$

$$\begin{aligned}
 &= m [\vec{v} \cdot \hat{v}] \hat{v} \\
 &= m v \hat{v} = m \vec{v}
 \end{aligned}$$

或者 $E_k = \frac{1}{2} m v^2$

$$\frac{\partial E_k}{\partial \vec{v}} = \frac{\partial E_k}{\partial v} \hat{v} \quad (\text{用 "}' \text{"})$$

根据定义 $= m v \hat{v} = m \vec{v}$

$$\begin{aligned}
 \int \vec{F} \cdot d\vec{r} &= \int m \vec{a} \cdot d\vec{r} \\
 &= \int m \frac{d\vec{v}}{dt} \cdot d\vec{r} \\
 &= \int m \vec{v} \cdot d\vec{v} \\
 &= \int d\left(\frac{1}{2} m v^2\right) = \Delta E_k
 \end{aligned}$$